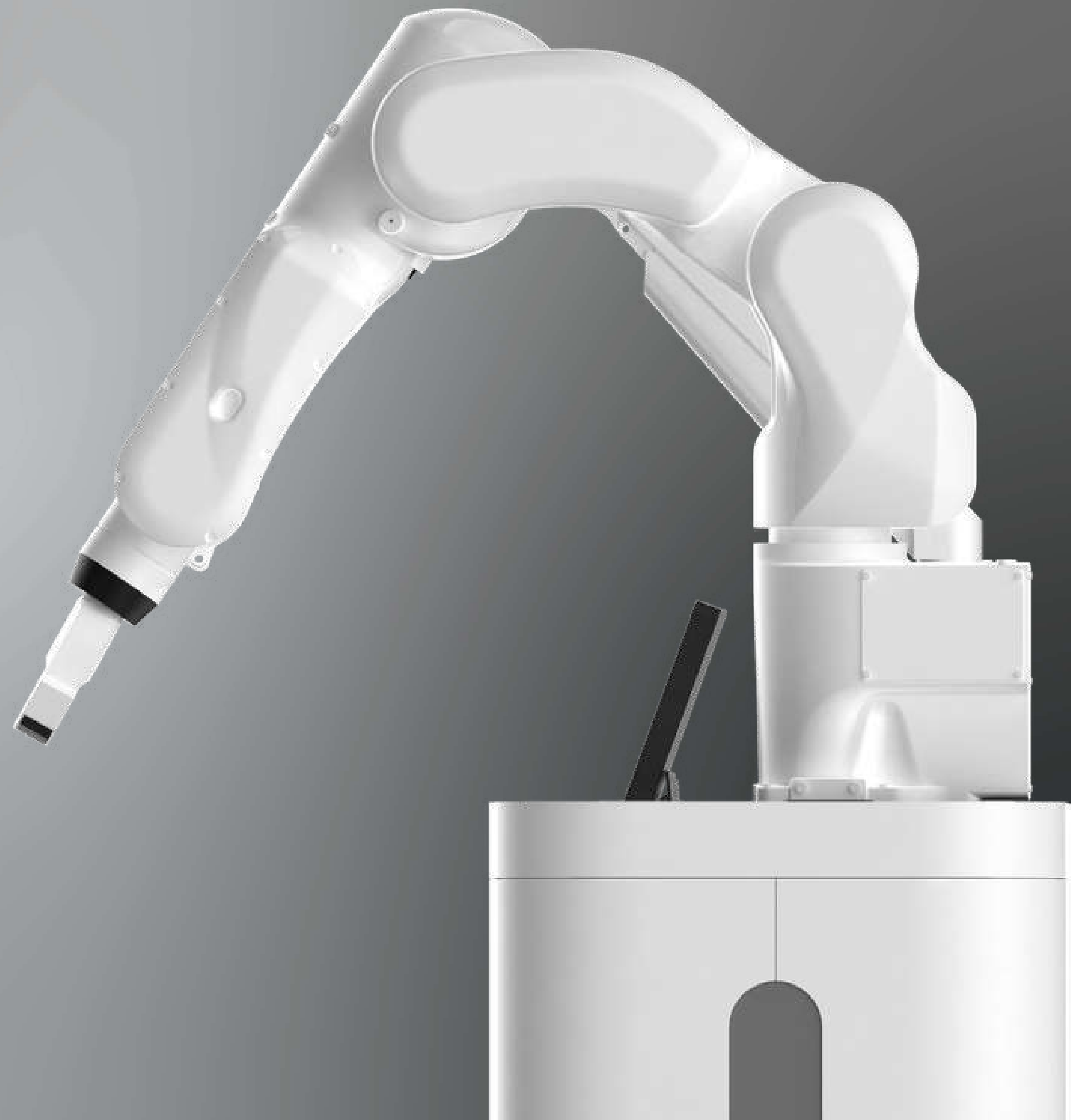
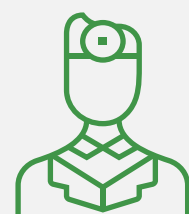


RoboScan



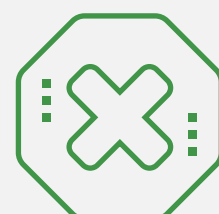
ROBOTIC AUTONOMOUS COMPLEX
FOR ULTRASONIC DIAGNOSTICS

Problem

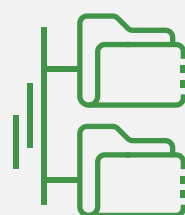


MARKED OPERATOR-DEPENDENCE

Localization of doctors in large cities, shortage in remote regions



WEAK STANDARDIZATION AND FORMALIZATION OF ULTRASOUND

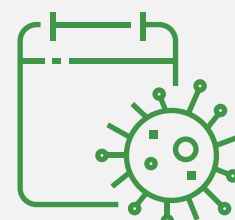


LACK OF COLLECTION AND ACCUMULATION OF PRIMARY INFORMATION IN ROUTINE ULTRASOUND PRACTICE



EXTENDED PROCEDURE DURATION

Because of the need for repeated manipulation of the physician during the examination



THE RISK OF INFECTING A PHYSICIAN

Because of the need to be in close proximity to an infected patient



HIGH COST OF THE PROCEDURE

Because of expensive specialists

Separation of ultrasound data acquisition and analysis processes

1. Ultrasound data collection

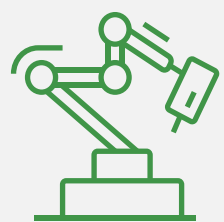
Automated examination mode	Robot + Lab technician
Remote control function	Robot + Lab technician
Separation of data collection and analysis of results	Robot + Lab technician

2. Saving initial data in DICOM

3. Data research

Expert data analysis	Physician
Decision Support System	AI + Physician
Automated analysis process	AI

Solution



SAVING RESOURCES

The possibility of ultrasound without or with minimal involvement of a human operator (lab technician)



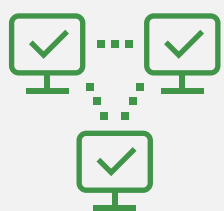
SAVING TIME

Routine work (data collection) is formalized and standardized



QUALITY IMPROVEMENT

By automating the screening process and forming centers of excellence using telemedicine technologies, quality expertise



REMOTE ACCESS

Allows physicians to work with hard-to-reach regions and eliminates the need for direct contact with infected patients



DATA ANALYSIS

Data accumulation, storage, and analysis will allow: faster examinations, prediction of diagnosis and treatment options



CREATING NEW SOLUTIONS

Forming an extensive dataset for research, new product creation, development and training of medical programs based on Machine Learning

Composition of the complex

Diagnostic site

ROBOTIC ARM



- Ultrasound machine
- Collaborative robotic manipulator, which implements the screening process in automated mode according to a predetermined trajectory, depending on the study area

The doctor's workplace

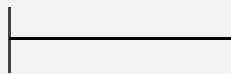
DATA
MANAGEMENT AND
ANALYSIS SYSTEM



- Converting received data to DICOM
- 3D modeling of the examined organ
- Physician's work interface with the display of the marked data of the ultrasound
- Accumulation, storage and analysis of examination results

Target markets

B2B



Private
medical centers

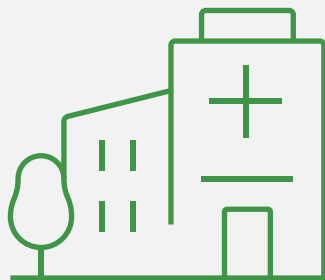
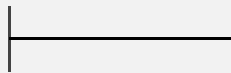


Medical equipment
manufacturers

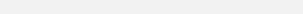


Manufacturers
of medical
complexes

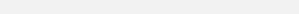
B2G



State medical
institutions

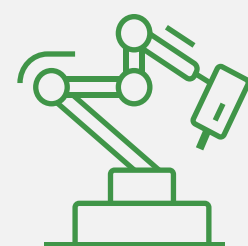


Defense
structures



MES

Current status



MVP, capable of performing automated examination of the pelvic area



Algorithms of formation and automatic analysis of ultrasound images



A platform for secure storage, processing and visualization of medical data

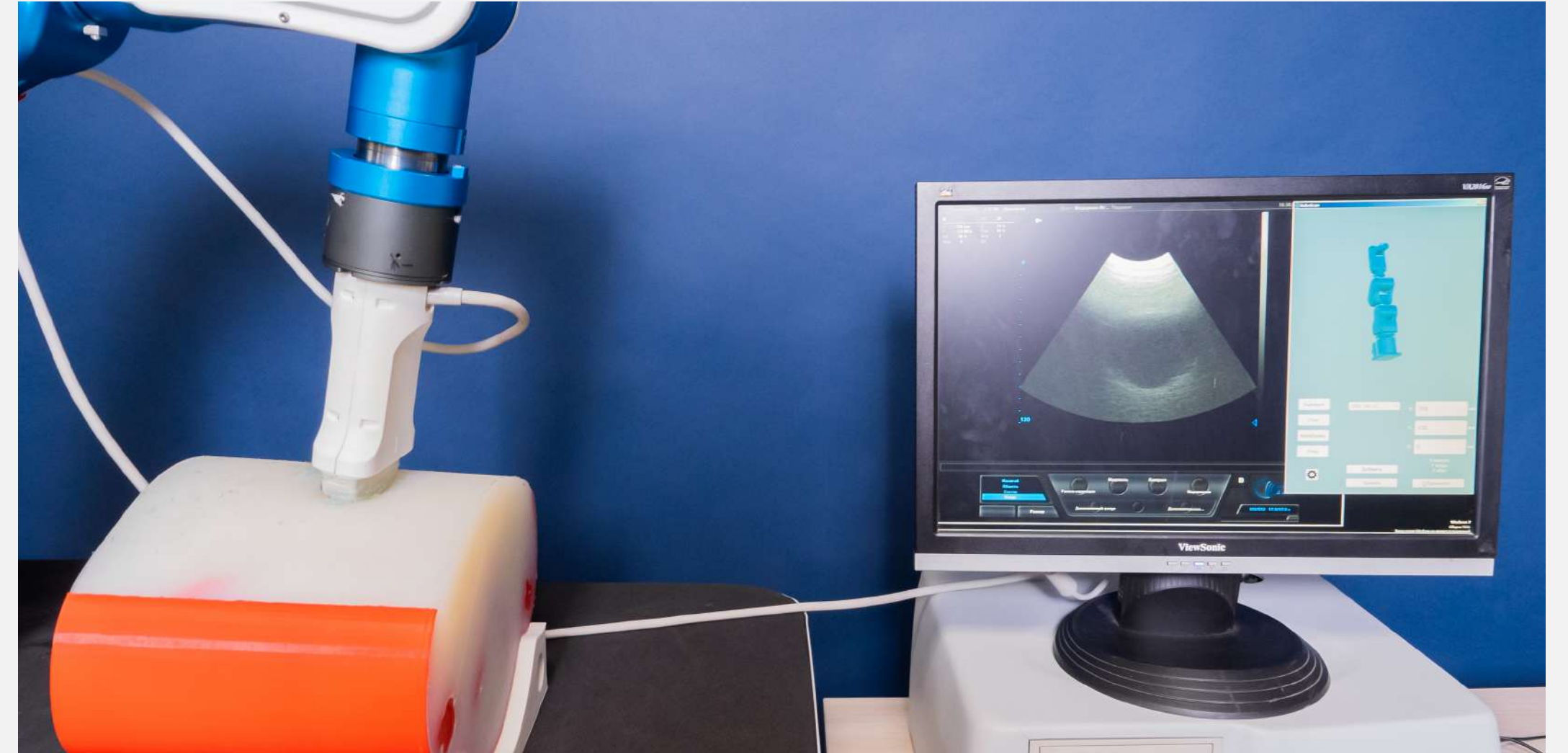


Strain gauge to regulate the degree of pressure



Developed ergonomic solutions

Current status



MVP, capable of performing automated examination of the pelvic area

Partners



Skolkovo
Innovation Center

Member of the
Skolkovo project



Moscow
Innovation Cluster

Cluster member



Sechenov
University

Testing of the
prototype complex



Manufacturer and
distributor of medical
devices and consumables

Production
and distribution

Team



Artem Badriev
CEO

Managing Director
at Rocketax Startup Studio



Nikolay Nagulin
CTO

Ph.D. Full member of the Academy of Medical
and Technical Sciences. CEO at Spectromed LLC



Igor Shaderkin
Medical Expert

Candidate of Medical Sciences. Head of
Laboratory, Institute of Digital Medicine,
Sechenov University. Expert in the field
of ultrasound diagnostics



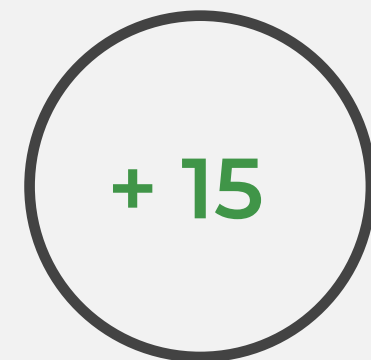
Vitaly Polyansky
Software Development Manager

Ph.D. Associate Professor, Department of Aviation Robotics
Systems, MAI. Civil Robotics Design Team Leader. Head of
scientific-educational center "Mechatronics, robotics and
intelligent systems"



Sergey Smirnov
Chief Designer

Associate Professor. Director of the Scientific and
Educational Center for Research and Innovative
Developments at the Stroganov Academy.
CEO at Smirnov Design LLC



A team of developers,
engineers and industrial
designers

RoboScan

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